95響年度博士刊王入雍考試

## Linear Algebra

## Notations．

－The notation $M_{n}(\mathbb{R})$ denotes the set of all $n \times n$ matrices over $\mathbb{R}$ ，and $I_{n}$ is the identity matrix in $M_{n}(\mathbb{R})$ ．
－For a matrix $A$ ，we let $A^{t}$ denote the transpose of $A$ ．

## Problems．

1．Let $\left\{e_{1}, e_{2}, e_{3}\right\}$ be the standard basis for $\mathbb{R}^{3}$ ．Suppose that a linear transformation $T: \mathbb{R}^{3} \mapsto \mathbb{R}^{3}$ is defined by $T(x, y, z)=(2 x+y, 2 y+$ $z, 2 z)$ ．
（1）Write down the matrix of $T$ relative to the standard basis．（2 points．）
（2）Write down the matrix of $T$ relative to the ordered basis $\left\{e_{3}, e_{2}, e_{1}\right\}$ ． （2 points．）
（3）Find a matrix $P$ such that

$$
P^{-1}\left(\begin{array}{lll}
a & 1 & 0 \\
0 & a & 1 \\
0 & 0 & a
\end{array}\right) P=\left(\begin{array}{lll}
a & 0 & 0 \\
1 & a & 0 \\
0 & 1 & a
\end{array}\right)
$$

for all real numbers $a$ ．（3 points．）
（4）Prove that for any given $n \times n$ matrix $A$ ，there is a matrix $Q$ such that

$$
Q^{-1} A Q=A^{t}
$$

（That is，$A$ and $A^{t}$ are similar for all square matrices $A$ ．）（8 points．）
（5）Let

$$
A=\left(\begin{array}{ccc}
1 & -1 & 0 \\
1 & 2 & 1 \\
0 & 1 & 1
\end{array}\right)
$$

Find a matrix $Q$ such that $Q^{-1} A Q=A^{t}$ ．（10 points．）
2．For an $n \times n$ matrix $A$ ，define

$$
\exp A=I_{n}+\sum_{k=1}^{\infty} \frac{A^{k}}{k!}
$$

Prove or disprove（by giving counterexamples）the following two asser－ tons．
（1）If $A$ is nilpotent，then so is $\exp A-I_{n}$ ．（ 8 points．）
（2）If $\exp A-I_{n}$ is nilpotent，then so is $A$ ．（ $\mathbf{7}$ points．）
3．Let $V=M_{n}(\mathbb{R})$ be the vector space of all $n \times n$ matrices over $\mathbb{R}$ ．For a given matrix $A \in M_{n}(\mathbb{R})$ ，define a linear operator $T_{A}$ on $V$ by

$$
T_{A}(B)=A B-B A, \quad \forall B \in V .
$$

(1) Consider the case $n=3$ and

$$
A=\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 2 & 0 \\
0 & 0 & 3
\end{array}\right)
$$

Determine the eigenvalues of $T_{A}$ and the associated eigenspaces. Determine also the minimal polynomial of $T_{A}$. ( 15 points.)
(2) For general $n$, consider the family

$$
\mathcal{F}=\left\{T_{A}: A \in M_{n}(\mathbb{R}) \text { are diagonal matrices. }\right\}
$$

of linear operators. Prove that $\mathcal{F}$ is simultaneously diagonalizable. (10 points.)
4. Let $V$ be an inner product space of finite dimension $n$ over $\mathbb{R}$. Recall that a linear transformation $T: V \mapsto V$ is called an isometry if $\left\langle T v_{1}, T v_{2}\right\rangle=\left\langle v_{1}, v_{2}\right\rangle$ for all $v_{1}, v_{2} \in V$.
(1) Prove that a linear transformation $T$ is an isometry if and only if its matrix with respect to an orthonormal basis is orthogonal. (An orthogonal matrix is a square matrix $M$ such that $M^{t} M=I_{n}$.) ( 10 points.)
(2) Consider the case $V=\mathbb{R}^{n}$ with the standard inner product. Let $v$ be a vector of unit length, and define a linear transformation $T_{v}$ by

$$
T_{v}(u)=u-2\langle u, v\rangle v \quad \text { for } u \in V
$$

Prove that $T_{v}$ is an isometry of $\mathbb{R}^{n}$. (We call such linear transformations reflections.) (5 points.)
(3) Consider $V=\mathbb{R}^{2}$ with the standard inner product. Prove that the linear transformation $S_{\theta}(x, y)=(x \cos \theta+y \sin \theta,-x \sin \theta+$ $y \cos \theta$ ) is an isometry of $\mathbb{R}^{2}$ for all real numbers $\theta$. (We call such linear transformation rotations.) (3 points.)
(4) Prove that every isometry of $\mathbb{R}^{2}$ is either a rotation or a reflection. ( 7 points.)
5. Let $V=M_{n}(\mathbb{R})$ be the vector space of all $n \times n$ matrices over $\mathbb{R}$, and $f: V \mapsto \mathbb{R}$ be a linear transformation. Assume that $f(A B)=f(B A)$ for all $A, B \in V$ and $f\left(I_{n}\right)=n$. Prove that $f$ is the trace function. (Hint: Consider the cases $A=e_{i j}, B=e_{k l}$ for various $i, j, k, l$, where $\left\{e_{i j}\right\}$ is the standard basis for $V$.) (10 points.)

